

Solutions to Midterm ECO 325 F (2009)

1. (a) C.R.T.S. implies $cF(K(t), A(t)L(t)) = F(cK(t), cA(t)L(t))$
for all $c \geq 0$ (*) (2 pts)

$$cF(K(t), A(t)L(t)) = c [K(t)^{\alpha_1} (A(t)L(t))^{\alpha_2}]^{\alpha_3} + c\alpha_4 A(t)L(t)$$

$$\stackrel{\text{also}}{=} F(cK(t), cA(t)L(t)) = [(cK(t))^{\alpha_1} (cA(t)L(t))^{\alpha_2}]^{\alpha_3} + \alpha_4 cA(t)L(t)$$

$$= [c^{\alpha_1} K(t)^{\alpha_1} c^{\alpha_2} (A(t)L(t))^{\alpha_2}]^{\alpha_3} + c\alpha_4 A(t)L(t)$$

$$= c^{(\alpha_1 + \alpha_2)\alpha_3} [K(t)^{\alpha_1} (A(t)L(t))^{\alpha_2}]^{\alpha_3} + c\alpha_4 A(t)L(t)$$

Since C.R.T.S. implies (*), for the function to exhibit C.R.T.S.
~~the~~ the following must hold.

$$\boxed{(\alpha_1 + \alpha_2)\alpha_3 = 1}$$

(2 pts)

and there are no restrictions on α_4
(2 pts)

b) The intensive form of the production function is given
by $y(t) = \frac{K(t)^{.34} (A(t)L(t))^{.66} + 2A(t)L(t)}{A(t)L(t)} = \left(\frac{K(t)}{A(t)L(t)}\right)^{.34} + 2$

$$= k(t)^{.34} + 2 = f(k(t))$$

(2 pts) for knowing def'n $y(t) = \frac{F(K(t), A(t)L(t))}{A(t)L(t)}$

(4 pts) for correct derivation.

c) (i) $f'(k(t)) = (.34) k(t)^{-.66}$, when $k(t) > 0$, then $f'(k(t))$
is positive \therefore the marginal product of capital per unit of
effective labour is positive

$$c) \text{ ii) } f''(k(t)) = (0.34)(-0.66) k(t)^{-1.66} < 0$$

when $k(t) > 0$. \therefore the intensive form of the production function is consistent with diminishing marginal returns on capital per unit of effective labour.

iii) The Inada conditions are

$$\lim_{k(t) \rightarrow 0} f'(k(t)) = \infty \quad \text{and} \quad \lim_{k(t) \rightarrow \infty} f'(k(t)) = 0$$

$$\text{so } \lim_{k(t) \rightarrow 0} (0.34) k(t)^{-0.66} = \infty \quad \text{and} \quad \lim_{k(t) \rightarrow \infty} (0.34) k(t)^{-0.66} = 0$$

\therefore the intensive form of the production function is consistent with the Inada conditions

$$2. (a) \ln Y(t) = \alpha \ln K(t) + (1-\alpha) \ln L(t) + (1-\alpha) \ln A(t)$$

6 pts $\frac{d \ln Y(t)}{dt} = \frac{\dot{Y}(t)}{Y(t)} = \alpha \frac{\dot{K}(t)}{K(t)} + (1-\alpha) \frac{\dot{L}(t)}{L(t)} + (1-\alpha) \frac{\dot{A}(t)}{A(t)}$

then since the growth rate of output per person is given by

only final eqn 3 pts $\frac{\dot{Y}(t)}{Y(t)} - \frac{\dot{L}(t)}{L(t)}$, we have

$$\frac{\dot{Y}(t)}{Y(t)} - \frac{\dot{L}(t)}{L(t)} = \alpha \frac{\dot{K}(t)}{K(t)} - \alpha \frac{\dot{L}(t)}{L(t)} + (1-\alpha) \frac{\dot{A}(t)}{A(t)}$$

2 b) $\alpha_K = \frac{\partial Y(t)}{\partial K(t)} \cdot \frac{K(t)}{Y(t)}$ by def'n. (2 pts)

so $\alpha_K = \frac{\alpha K(t)^{\alpha-1} (A(t)L(t))^{1-\alpha} \cdot K(t)}{K(t)^\alpha (A(t)L(t))^{1-\alpha}} = \alpha$ Q.E.D

(2 pts for derivation)

c) $\alpha_L = \frac{\partial Y(t)}{\partial L(t)} \cdot \frac{L(t)}{Y(t)} = \frac{(1-\alpha) K(t)^\alpha L(t)^{-\alpha} A(t)^{1-\alpha} L(t)}{K(t)^\alpha (A(t)L(t))^{1-\alpha}}$

(4 pts)

$= (1-\alpha)$

so $\alpha_K + \alpha_L = \alpha + 1-\alpha = 1$ Q.E.D.

d) Given $\frac{\dot{Y}(t)}{Y(t)} - \frac{\dot{L}(t)}{L(t)} = 5\%$, $\alpha = \frac{1}{3}$

and $\frac{\dot{K}(t)}{K(t)} - \frac{\dot{L}(t)}{L(t)} = 3\%$

so the solow residual

$R(t) = (1-\alpha) \frac{\dot{A}(t)}{A(t)} = \frac{\dot{Y}(t)}{Y(t)} - \frac{\dot{L}(t)}{L(t)} - \left(\frac{1}{3}\right) \left(\frac{\dot{K}(t)}{K(t)} - \frac{\dot{L}(t)}{L(t)}\right)$

$\frac{\dot{Y}}{Y} = \alpha \frac{\dot{K}}{K} + (1-\alpha) \frac{\dot{L}}{L} + (1-\alpha) \frac{\dot{A}}{A} = 5\% - \left(\frac{1}{3}\right)(3\%) = 4\%$

e) The solow residual tells us what component of growth in output is attributable to changes in knowledge (2 pts)

$$3. (a) \quad U = \int_{t=0}^{\infty} e^{-\rho t} (C(t)^\theta + 1) \frac{L(t)}{H} dt$$

$$= \int_{t=0}^{\infty} e^{-\rho t} \left(\underbrace{(C(t)A(t))^\theta}_{1 \text{ pt}} + 1 \right) \frac{L(t) e^{nt}}{H} dt = \int_{t=0}^{\infty} e^{-\rho t} \underbrace{C(t)^\theta}_{1 \text{ pt}} \underbrace{(A(t) e^{\delta t})^\theta}_{1 \text{ pt}} \underbrace{L(t) e^{nt}}_{1 \text{ pt}} dt + \int_{t=0}^{\infty} \frac{e^{-\rho t} L(t) e^{nt}}{H} dt$$

$$= \frac{A(0)^\theta L(0)}{H} \int_{t=0}^{\infty} e^{-(\rho - n - \theta g)t} C(t)^\theta dt + \frac{L(0)}{H} \int_{t=0}^{\infty} e^{-(\rho - n)t} dt \quad 2 \text{ pts}$$

4 pts for derivation

$$- \frac{L(0)}{H(\rho - n)} e^{-(\rho - n)t} \Big|_0^\infty = \frac{L(0)}{H(\rho - n)} \text{ finite}$$

b) $\rho - n - \theta g$ must be greater than 0 to ensure lifetime utility is bounded (i.e., its value $< \infty$)

3 pts

$$c) \quad \mathcal{L} = \frac{A(0)^\theta L(0)}{H} \int_{t=0}^{\infty} e^{-(\rho - n - \theta g)t} C(t)^\theta dt + \frac{L(0)}{H} \int_{t=0}^{\infty} e^{-(\rho - n)t} dt$$

$$+ \lambda \left[R(0) + \int_{t=0}^{\infty} e^{-R(t)} w(t) e^{(n+g)t} dt - \int_{t=0}^{\infty} e^{-R(t)} C(t) e^{(n+g)t} dt \right]$$

$$\frac{\partial \mathcal{L}}{\partial C(t)} = \frac{A(0)^\theta L(0)}{H} e^{-(\rho - n - \theta g)t} \theta C(t)^{\theta-1} - \lambda e^{-R(t)} e^{(n+g)t} = 0$$

for all t .

2 pts

3 c) cont. $\frac{\partial \mathcal{L}}{\partial r(t)} = 0 \Leftrightarrow \lambda e^{-R(t)t} e^{(n+g)t} = \frac{A(t)^\theta L(t)^\theta}{H} e^{-(\rho-n-g)t} \theta r(t)^{\theta-1}$

or

$$\ln \lambda - R(t) + (n+g)t = \ln\left(\frac{A(t)^\theta L(t)^\theta}{H}\right) - (\rho-n-g)t + (\theta-1) \ln r(t)$$

since this holds for all date t , take the derivative w.r.t. t to get

(2 pts) $-\frac{\partial R(t)}{\partial t} + (n+g) = -\rho + n + g + (\theta-1) \frac{\dot{r}(t)}{r(t)}$

Since $\frac{\partial R(t)}{\partial t} = r(t)$, we get $\frac{\dot{r}(t)}{r(t)} = \frac{r(t) - \rho - (\theta-1)g}{(1-\theta)}$

(4 pts) d) $\max_{K(t), L(t)} F(K(t), A(t)L(t)) - r(t)K(t) - w(t)A(t)L(t)$
 (1 pt) \uparrow (1 pt) \uparrow

e) the problem in d) can be written as

$$\max_{K(t), L(t)} A(t)L(t) f\left(\frac{K(t)}{A(t)L(t)}\right) - r(t)K(t) - w(t)A(t)L(t)$$

then the first order conditions are

$$K(t): A(t)L(t) f'\left(\frac{K(t)}{A(t)L(t)}\right) \cdot \frac{1}{A(t)L(t)} - r(t) = 0$$

$$\Leftrightarrow f'(k(t)) = r(t)$$

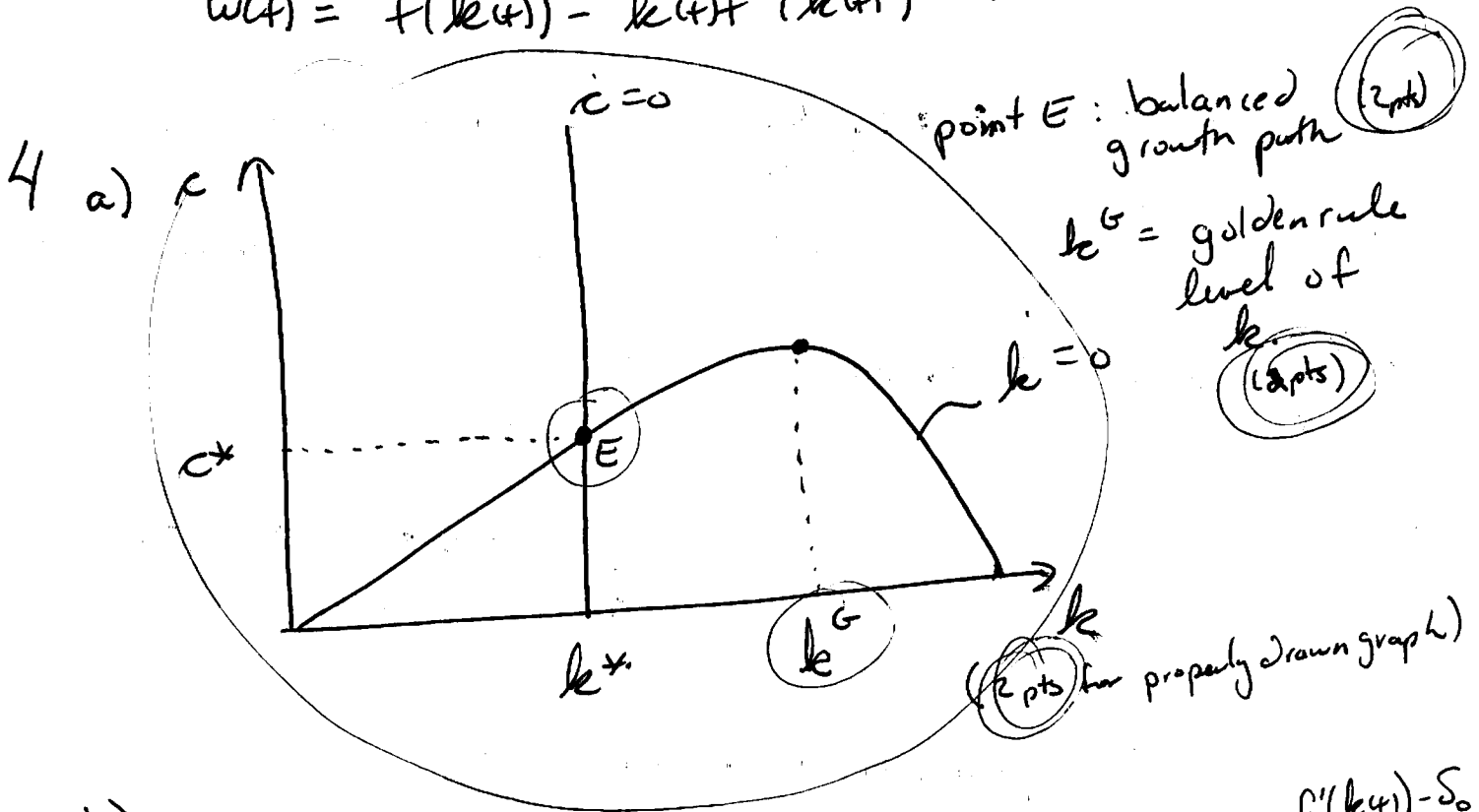
$$L(t): A(t) f\left(\frac{K(t)}{A(t)L(t)}\right) + A(t)L(t) f''\left(\frac{K(t)}{A(t)L(t)}\right) \left(\frac{-K(t)}{A(t)L(t)^2}\right) - w(t)A(t) = 0$$

3 pts for this derivation

3 pts for this derivation

which can be rewritten as:

$$w(t) = f(k(t)) - k(t)f'(k(t)) \text{ as desired}$$



b) (i) let $\delta_0 < \delta_1$, $\frac{\dot{c}(t)}{c(t)} = \frac{r(t) - \rho - \theta y}{\theta}$ where $r(t) = f'(k(t)) - \delta_0$

as $\dot{c}(t) = 0 \Rightarrow f'(k_{old}^*) - \delta_0 - \rho - \theta y = 0$ or $f'(k_{old}^*) = \delta_0 + \rho + \theta y$

also $\dot{c}(t) = 0 \Rightarrow f'(k_{new}^*) - \delta_1 - \rho - \theta y = 0$ or $f'(k_{new}^*) = \delta_1 + \rho + \theta y$

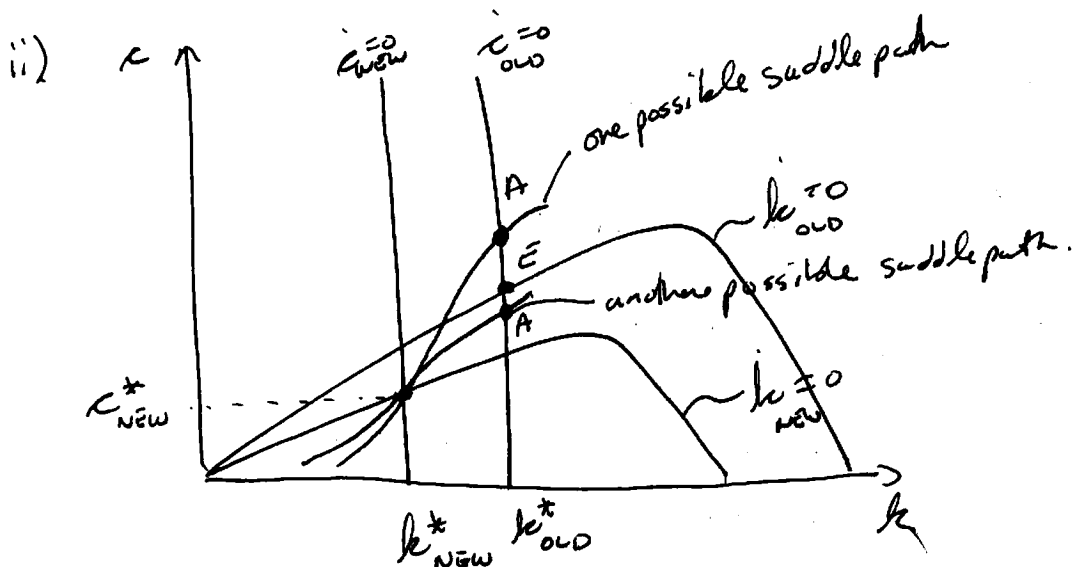
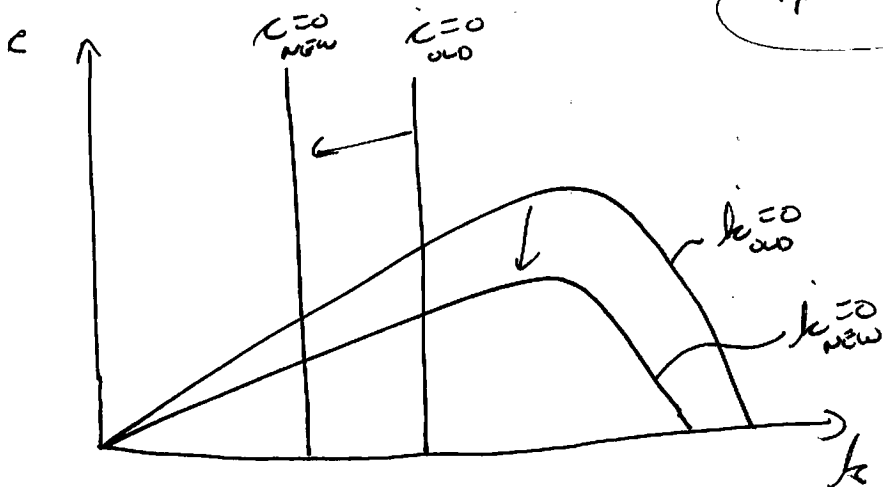
since $\delta_0 < \delta_1$, $f'(k_{old}^*) < f'(k_{new}^*)$ so $k_{old}^* > k_{new}^*$

(since $f''(k) < 0$) $\therefore \dot{c} = 0$ curve shifts in
 (1 pt for derivation, 1 pt for correct shift)

$k_{old}^* = 0$ is given by $0 = f(k(t)) - c(t) - (n+g+\delta_0)k(t)$
 $\Leftrightarrow c(t) = f(k(t)) - (n+g+\delta_0)k(t)$

$k_{new}^* = 0$ is given by $0 = f(k(t)) - c(t) - (n+g+\delta_1)k(t)$
 $\Leftrightarrow c(t) = f(k(t)) - (n+g+\delta_1)k(t)$

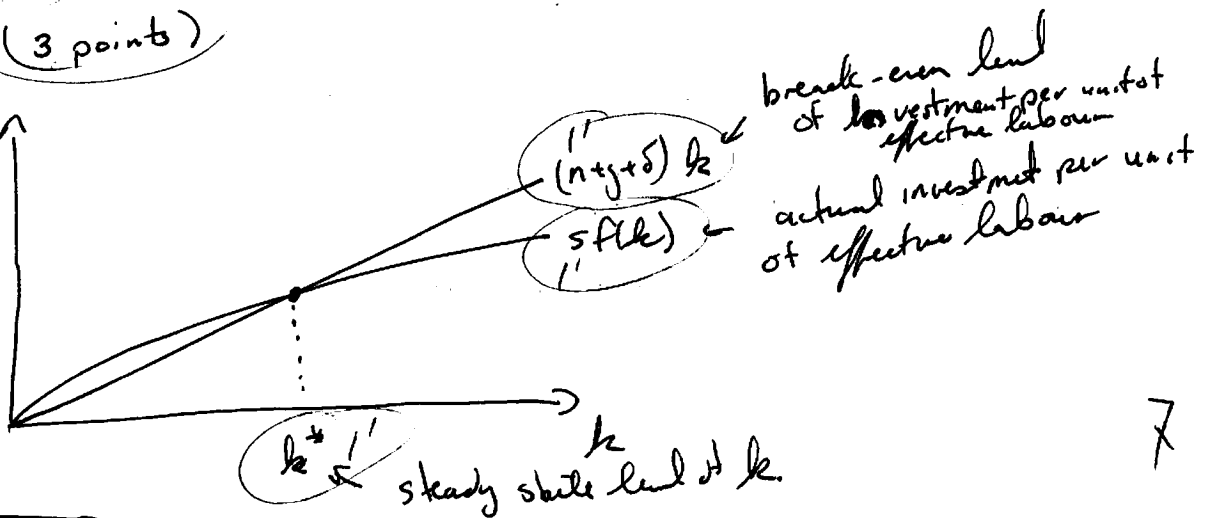
4 b) i) cont. since $\delta_1 > \delta_0$, the $k=0$ curve moves downwards (see graph) (1 pt for derivation, 1 pt for correct movement)



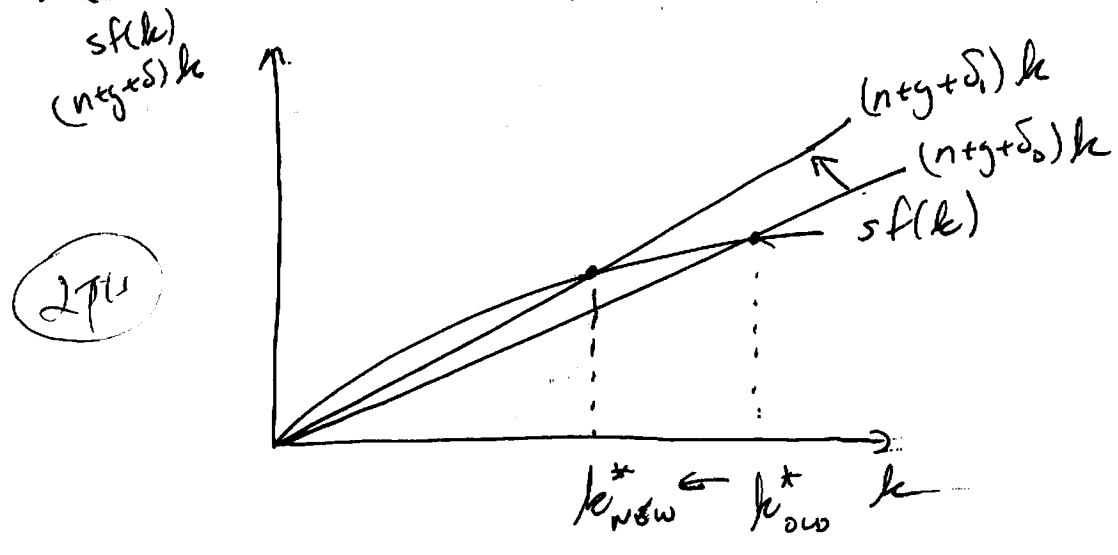
at the time of this change c will either rise, fall or stay the same - it depends on where the saddle path cuts the old $c=0$ curve (see points A on the graph above)

(3 points)

c) $s f(k)$
 $(n+\delta)k$
 (3 pts)



d) (i) $\delta \uparrow$ raises the slope of the break-even curve



$\delta_1 > \delta_0$

1 pt for proper movement of k^*

1 pt for properly labelled graph

(ii) $sf(k^*) = (n+g+\delta)k^*$ Note k^* is a fun of δ
 so $sf'(k^*) \frac{dk^*}{d\delta} = k^* + (n+g+\delta) \frac{dk^*}{d\delta}$

or $\frac{dk^*}{d\delta} = \frac{k^*}{sf'(k^*) - (n+g+\delta)} < 0$ since $sf'(k^*) < (n+g+\delta)$

1 pt for sign, 1 pt for derivation

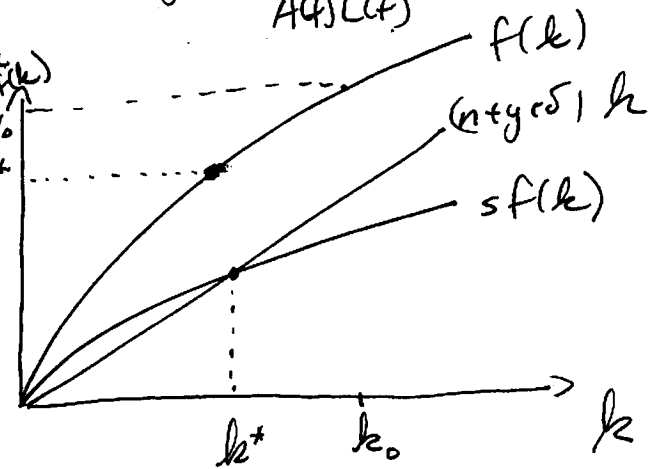
iii) at the time of the change $c(t) = (1-s)f(k(t))$ and since $k(t)$ does not instantaneously respond, $c(t)$ does not immediately change (3 pts)

e) i) A one time unexpected decrease in the level of knowledge in the economy has no impact on n, g, δ or s in the Solow model and has no effect on δ, n, g, ρ or θ in the Ramsey-Cass Koopman model \therefore this shock has no impact on the Balanced growth path in either model (3 pts)

e) i) The golden rule level of k is given by $f'(k^G) = (n+g+\delta)$, which is unchanged in either model. However, to get the per person level of k^G we need to multiply by $A(t)$, which initially drops to its new value & then grows at rate g thereafter. (3 pts)

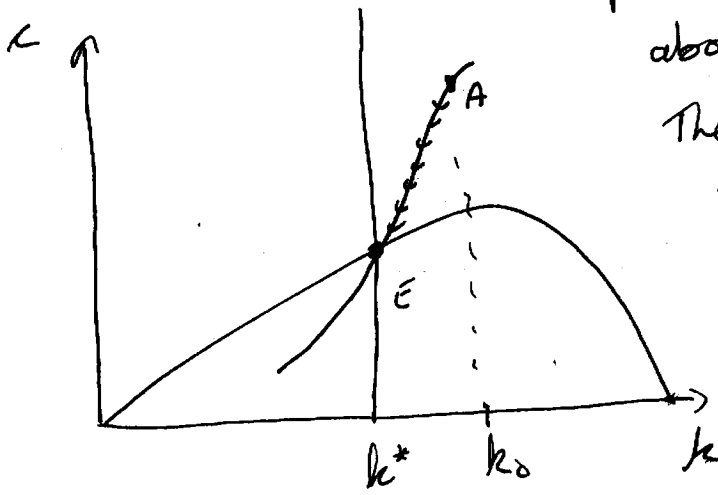
ii) $k(t) = \frac{K(t)}{A(t)L(t)}$ and $y(t) = \frac{Y(t)}{A(t)L(t)}$

In the Solow model over time a decrease in A causes k to rise above its steady state level, k^* , to a point like k_0 . At this point $\dot{k}(t) < 0$, so k decreases back towards k^* . When $k(t)$ reaches k^* , the economy is again on its balanced growth path and stops changing. Also since $y(t) = f(k(t))$, $\dot{y}(t) = f'(k(t)) \cdot \dot{k}(t)$, so $y(t)$ initially rises to y_0 , then decreases, as $k(t)$ decreases, back to its original steady state level y^* . When $k(t)$ reaches k^* , $y(t)$ reaches y^* and $y(t)$ no longer changes.



2 pts for Δ in k , 2 pts for Δ in y .

In the Ramsey-Cass-Koopman model, we see a similar pattern. When A drops, $k(t)$ rises above its steady state value, k^* .



The economy then moves along its saddle path. From point A , back to point E and as it does $k(t)$ falls. When the economy is again at point E , $k(t)$

is back at its original level k^* , and no longer changes (unless another shock hits). Similarly since $y(t) = f(k(t))$, $y(t) = f'(k(t))k(t)$, so $y(t)$ initially increases to $y_0 = f(k_0)$ then decreases as $k(t)$ falls from k_0 to k^* , and when k reaches its steady state value k^* , y^* returns to $y^* = f(k^*)$ and also no longer changes.

(2 pts for Δk , 2 pts for Δy)